Spin chains based on (quantum) gl(3) algebras: Bethe vectors, scalar products and form factors

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General background

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Bethe vectors

Correlation functions

Multiple actions of $T_{ij}(\bar{x})$ on BVs

Scalar products of BVs

Form factors (off-diagonal case)

Form factors (diagonal case)

Form factors (remaining)

Summary

Case of trigonometric R-matrices

General background: Integrable spin chains

Rational or trigonometric 9×9 *R*-matrix

 $R(x, y) \in V \otimes V$ with $V = End(\mathbb{C}^3)$

R(x, y) obeys Yang-Baxter equation (in $V \otimes V \otimes V$)

 $R^{12}(x_1, x_2) R^{13}(x_1, x_3) R^{23}(x_2, x_3) = R^{23}(x_2, x_3) R^{13}(x_1, x_3) R^{12}(x_1, x_2)$

It is associated to a quantum group $\mathcal A$ which is:

- The Yangian $\mathcal{A} = Y(g_{3})$ when R(x, y) is rational (XXX chain)
- ► The affine quantum group A = U_q(gl₃) when R(x, y) is trigonometric (XXZ chain)

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For the talk, rational *R*-matrix:

$$R(x,y) = \mathbf{I} + g(x,y)\mathbf{P} \in End(\mathbb{C}^3) \otimes End(\mathbb{C}^3)$$
 and $g(x,y) = \frac{c}{x-y}$

I is the identity matrix, **P** is the permutation matrix between two spaces $End(\mathbb{C}^3)$, *c* is a constant.

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Monodromy matrix

$$T(x) = \sum_{i,j=1}^{3} e_{ij} \otimes T_{ij}(x) \in \mathsf{End}(\mathbb{C}^{3}) \otimes \mathcal{A}$$

T(x) obeys the RTT commutation relations:

$$R^{12}(x,y) T^{1}(x) T^{2}(y) = T^{2}(y) T^{1}(x) R^{12}(x,y)$$

This defines the quantum group \mathcal{A} It leads to an integrable model through the transfer matrix

$$t(x) = tr_0 T^0(x) = T_{11}(x) + T_{22}(x) + T_{33}(x) \in \mathcal{A}$$

[t(x), t(y)] = 0

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Choice of a $Y(gl_3)$ (lowest weight) representation:

$$T_{jj}(w)|0
angle = \lambda_j(w)|0
angle, \ j = 1, 2, 3$$
 $T_{ij}(w)|0
angle = 0,$ $1 \le j < i \le 3$

Up to normalisation $T(w) \rightarrow \lambda_2^{-1}(w)T(w)$, only need the ratios

$$r_1(w) = rac{\lambda_1(w)}{\lambda_2(w)}, \qquad r_3(w) = rac{\lambda_3(w)}{\lambda_2(w)}.$$

where r_1 and r_3 are free functional parameters.

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Aim

Compute the correlation functions $\langle \mathcal{O}_1 \cdots \mathcal{O}_n \rangle = tr(\mathcal{O}_1 \cdots \mathcal{O}_n)$ for some local operators $\mathcal{O}_1, \cdots, \mathcal{O}_n$

If one has a basis of the space of states $\mathcal{H}, \, \{|\psi>\},$ then it is enough to compute $<\psi'|\mathcal{O}_1\cdots\mathcal{O}_n|\psi>$ Since we have a basis $\mathcal{O}|\psi>=\sum <\psi'|\mathcal{O}|\psi>$, and we need "only" $<\psi|\psi'>$ Spin chains based on (quantum) gl(3) algebras: Bethe vectors, scalar products and form factors

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Aim

• Compute Bethe vectors (BVs), eigenvectors of t(x):

 $t(x) \mathbb{B}^{a,b}(\bar{u},\bar{v}) = \tau(x|\bar{u},\bar{v}) \mathbb{B}^{a,b}(\bar{u},\bar{v}) \Rightarrow \text{ Bethe ansatz eqs (BAE)}$

- Action of $T_{ij}(\bar{x})$ on $\mathbb{B}^{a,b}(\bar{u},\bar{v})$
- Scalar product of off-shell BVs (without BAE)
- Form factors $\mathbb{C}^{a,b}(\bar{t},\bar{s})T_{ij}(\bar{x})\mathbb{B}^{a,b}(\bar{u},\bar{v})$

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Plan of the talk

- Bethe vectors (BVs)
- Multiple actions of Yangian generators on BVs
- Scalar products of BVs
- Form factors and correlation functions
- Conclusion

Calculations are rather technical \Rightarrow results only!

Presentation for $Y(gl_3)$ but most of the results are valid for $U_q(gl_3)$ (see at the end)

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Apart from the functions $g(x, y) = \frac{c}{x-y}$, $r_1(x)$ and $r_3(x)$ we introduce

$$f(x,y) = \frac{x-y+c}{x-y}, \quad h(x,y) = \frac{f(x,y)}{g(x,y)}, \quad t(x,y) = \frac{g(x,y)}{h(x,y)}.$$

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- "bar" always denote sets of variables: \bar{w} , \bar{u} , \bar{v} etc..
- ▶ |.| is the dimension of a set: $\bar{w} = \{w_1, w_2\} \Rightarrow |\bar{w}| = 2$, etc...
- ▶ Individual elements of the sets have latin subscripts: w_j, u_k, etc..
- Subsets of variables are denoted by roman indices: \bar{u}_{I} , \bar{v}_{iv} , \bar{w}_{II} , etc.
- Special case: $\bar{u}_j = \bar{u} \setminus \{u_j\}$, $\bar{w}_k = \bar{w} \setminus \{w_k\}$, etc...

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Shorthand notations for products of scalar functions:

$$f(\bar{u}_{\Pi},\bar{u}_{I}) = \prod_{u_{j}\in\bar{u}_{\Pi}}\prod_{u_{k}\in\bar{u}_{I}}f(u_{j},u_{k}),$$

$$r_{1}(\bar{u}_{\Pi}) = \prod_{u_{j}\in\bar{u}_{\Pi}}r_{1}(u_{j}); \quad g(v_{k},\bar{w}) = \prod_{w_{j}\in\bar{w}}g(v_{k},w_{j}), \quad etc..$$

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Bethe vectors

Framework: Algebraic-Nested Bethe ansatz (Leningrad school 80's) [Faddeev, Kulish, Reshetikhin, Sklyanin, Takhtajan]

On-shell Bethe vectors

$$t(x) \mathbb{B}^{a,b}(\bar{u};\bar{v}) = \tau(x|\bar{u};\bar{v}) \mathbb{B}^{a,b}(\bar{u};\bar{v})$$

 $\bar{u} = \{u_1, ..., u_a\}$ and $\bar{v} = \{v_1, ..., v_b\}$ are the Bethe parameters. t(x)-eigenvectors provided \bar{u} and \bar{v} obey the Bethe equations (BAEs):

$$\begin{aligned} r_1(\bar{u}_{\mathrm{I}}) &= \quad \frac{f(\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{II}})}{f(\bar{u}_{\mathrm{II}}, \bar{u}_{\mathrm{I}})} f(\bar{v}, \bar{u}_{\mathrm{I}}), \\ r_3(\bar{v}_{\mathrm{I}}) &= \quad \frac{f(\bar{v}_{\mathrm{II}}, \bar{v}_{\mathrm{II}})}{f(\bar{v}_{\mathrm{I}}, \bar{v}_{\mathrm{II}})} f(\bar{v}_{\mathrm{I}}, \bar{u}). \end{aligned}$$

that hold for arbitrary partitions of the sets \bar{u} and \bar{v} into subsets $\{\bar{u}_{I}, \ \bar{u}_{II}\}\$ and $\{\bar{v}_{I}, \ \bar{v}_{II}\}.$

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Known formulas: Trace formula ['07 Tarasov & Varchenko]

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = tr\Big(\mathbb{T}(\bar{u};\bar{v})\,\mathbb{R}(\bar{u};\bar{v})\,\mathbf{e}_{21}^{\otimes a}\otimes\,\mathbf{e}_{32}^{\otimes b}\Big)\in Y(gl_3)$$

where \mathbb{T} is some product of T(x)'s and \mathbb{R} of *R*-matrices.

Recursion formulas

$$\begin{split} \lambda_{2}(u_{k})f(\bar{v},u_{k})\mathbb{B}^{a+1,b}(\bar{u};\bar{v}) &= T_{12}(u_{k})\mathbb{B}^{a,b}(\bar{u}_{k};\bar{v}) + \\ &+ \sum_{i=1}^{b} g(v_{i},u_{k})f(\bar{v}_{i},v_{i})T_{13}(u_{k})\mathbb{B}^{a,b-1}(\bar{u}_{k};\bar{v}_{i}), \\ \lambda_{2}(v_{k})f(v_{k},\bar{u})\mathbb{B}^{a,b+1}(\bar{u};\bar{v}) &= T_{23}(v_{k})\mathbb{B}^{a,b}(\bar{u};\bar{v}_{k}) + \\ &+ \sum_{i=1}^{a} g(v_{k},u_{i})f(u_{j},\bar{u}_{j})T_{13}(v_{k})\mathbb{B}^{a-1,b}(\bar{u}_{j};\bar{v}_{k}). \end{split}$$

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Explicit formulas

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{\mathsf{K}_{k}(\bar{v}_{\mathrm{I}}|\bar{u}_{\mathrm{I}})}{\lambda_{2}(\bar{v}_{\mathrm{I}})\lambda_{2}(\bar{u})} \frac{f(\bar{v}_{\mathrm{I}},\bar{v}_{\mathrm{I}})f(\bar{u}_{\mathrm{I}},\bar{u}_{\mathrm{I}})}{f(\bar{v}_{\mathrm{I}},\bar{u})f(\bar{v}_{\mathrm{I}},\bar{u}_{\mathrm{I}})} T_{12}(\bar{u}_{\mathrm{I}})T_{13}(\bar{u}_{\mathrm{I}})T_{23}(\bar{v}_{\mathrm{I}})|0$$

Plus others with different order of T_{12} , T_{13} , T_{23}

The sums are taken over partitions of the sets $\bar{u} \Rightarrow \{\bar{u}_{I}, \bar{u}_{II}\}$ and $\bar{v} \Rightarrow \{\bar{v}_{I}, \bar{v}_{II}\}$ with $0 \le |\bar{u}_{I}| = |\bar{v}_{I}| = k \le \min(a, b)$.

 $K_k(\bar{v}_I | \bar{u}_I)$ is the Izergin–Korepin determinant

$$\mathsf{K}_k(\bar{x}|\bar{y}) = \prod_{\ell < m}^k g(x_\ell, x_m) g(y_m, y_\ell) \cdot h(\bar{x}, \bar{y}) \, \det_k \left[t(x_i, y_j) \right].$$

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All these formulas are related

- Explicit expressions obey the recursion formulas
- Trace formula obeys the recursion formulas
- ▶ Recursion formulas uniquely fix the BVs, once B^{a,0}(ū,.) or B^{0,b}(., v̄) are known.

Bethe vectors $\mathbb{B}^{a,b}(\bar{u};\bar{v})$, $|\bar{u}| = a$, $|\bar{v}| = b$

• On-shell BVs: \bar{u}, \bar{v} obey BAEs so that

$$t(x) \mathbb{B}^{a,b}(\bar{u};\bar{v}) = \tau(x|\bar{u};\bar{v}) \mathbb{B}^{a,b}(\bar{u};\bar{v})$$

• Off-shell BVs: \bar{u}, \bar{v} are left free

Dual Bethe vectors $\mathbb{C}^{a,b}(\bar{u};\bar{v})$, $|\bar{u}| = a$, $|\bar{v}| = b$

• On-shell dual BVs: \bar{u}, \bar{v} obey BAEs so that

$$\mathbb{C}^{a,b}(\bar{u};\bar{v}) t(x) = \tau(x|\bar{u};\bar{v}) \mathbb{C}^{a,b}(\bar{u};\bar{v})$$

• Off-shell dual BVs: \bar{u}, \bar{v} are left free

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How to compute $\mathcal{O}_{\mathbb{C},\mathbb{B}} = \langle \mathbb{C} | \mathcal{O} | \mathbb{B} \rangle$?

If $|\mathbb{B}\rangle$ is a complete basis (of transfer matrix eigenvectors), then

$$|\mathcal{O}|\mathbb{B}
angle = \sum_{\mathbb{B}'} \mathbb{O}_{\mathbb{B}\mathbb{B}'} |\mathbb{B}'
angle$$

ightarrow what is needed is $\langle \mathbb{C} | \mathbb{B}'
angle$ and (1)

$$\text{Local operators: } \mathcal{O} = \sum_{\ell=1}^{L} \sum_{i,j=1}^{3} \mathcal{O}_{ij}^{(\ell)} \, \mathbf{e}_{ij}^{\ell} \, \Rightarrow \, \langle \mathbb{C} | \mathbf{e}_{ij}^{\ell} | \mathbb{B} \rangle$$

Further simplification: QISM

Expression of e_{ij}^{ℓ} , i, j = 1, 2, 3 and $\ell = 1, ...L$, in terms of monodromy entries $T_{kl}(x)$ ['00 Maillet & Terras]:

$$e_{ij}^{\ell} = (t(0))^{\ell-1} T_{ij}(0) (t(0))^{-\ell}$$

 \Rightarrow we need "only" $T_{kl}(x)\mathbb{B}^{a,b}(\bar{u};\bar{v})$ and $\mathbb{C}^{a,b}(\bar{w};\bar{z})\mathbb{B}^{a,b}(\bar{u};\bar{v})$

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Multiple actions of $T_{ij}(\bar{x})$ on $\mathbb{B}^{a,b}(\bar{u};\bar{v})$

$$|\bar{x}| = n$$
, $\{\bar{u}, \bar{x}\} = \bar{\eta}$, $|\bar{\eta}| = a + n$; $\{\bar{v}, \bar{x}\} = \bar{\xi}$, $|\bar{\xi}| = b + n$

 $T_{13}(\bar{x})\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \lambda_2(\bar{x})\mathbb{B}^{a+n,b+n}(\bar{\eta};\bar{\xi}).$

 $T_{12}(\bar{x})\mathbb{B}^{a,b}(\bar{u};\bar{v}) = (-1)^n \lambda_2(\bar{x}) \sum f(\bar{\xi}_{\mathrm{II}},\bar{\xi}_{\mathrm{I}})\mathsf{K}_n(\bar{\xi}_{\mathrm{I}}|\bar{x}+c) \mathbb{B}^{a+n,b}(\bar{\eta};\bar{\xi}_{\mathrm{II}}).$ Sum on partitions $\bar{\xi} = \{\bar{\xi}_{\mathrm{I}};\bar{\xi}_{\mathrm{II}}\}$ with $|\bar{\xi}_{\mathrm{I}}| = n$

 $T_{23}(\bar{x})\mathbb{B}^{a,b}(\bar{u};\bar{v}) = (-1)^n \lambda_2(\bar{x}) \sum f(\bar{\eta}_{\mathrm{I}},\bar{\eta}_{\mathrm{II}}) \mathsf{K}_n(\bar{x}|\bar{\eta}_{\mathrm{I}}+c) \mathbb{B}^{a,b+n}(\bar{\eta}_{\mathrm{II}};\bar{\xi}).$

Sum on partitions $\bar{\eta} = \{\bar{\eta}_{\mathrm{I}}; \bar{\eta}_{\mathrm{II}}\}$ with $|\bar{\eta}_{\mathrm{I}}| = n$

Imply recursion relations as a subcase (n=1) Similar expressions for any $T_{ij}(\bar{x})$ and for dual BVs Spin chains based on (quantum) gl(3) algebras: Bethe vectors, scalar products and form factors

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Scalar products of BVs

$$\mathcal{S}_{a,b} \equiv \mathcal{S}_{a,b}(\bar{u}^{C}, \bar{u}^{B} | \bar{v}^{C}, \bar{v}^{B}) = \mathbb{C}^{a,b}(\bar{u}^{C}; \bar{v}^{C}) \mathbb{B}^{a,b}(\bar{u}^{B}; \bar{v}^{B})$$

Superscripts ^B and ^C to denote <u>different</u> sets of parameters!

General formula given by Reshetikhin

$$\begin{split} \mathcal{S}_{a,b} &= \sum r_{1}(\bar{u}_{1}^{B})r_{1}(\bar{u}_{1}^{C})r_{3}(\bar{v}_{1}^{B})r_{3}(\bar{v}_{1}^{C}) \\ &\times f(\bar{u}_{1}^{C},\bar{u}_{1}^{C})f(\bar{u}_{1}^{B},\bar{u}_{1}^{B})f(\bar{v}_{1}^{C},\bar{v}_{1}^{C})f(\bar{v}_{1}^{B},\bar{v}_{1}^{B})f(\bar{v}_{1}^{C},\bar{u}_{1}^{C})f(\bar{v}_{1}^{B},\bar{u}_{1}^{B}) \\ &\times Z_{a-k,n}(\bar{u}_{1}^{C};\bar{u}_{1}^{B}|\bar{v}_{1}^{C};\bar{v}_{1}^{B})Z_{k,b-n}(\bar{u}_{1}^{B};\bar{u}_{1}^{C}|\bar{v}_{1}^{B};\bar{v}_{1}^{C}) \\ \bar{u}^{B} &= \{\bar{u}_{1}^{B},\bar{u}_{1}^{B}\}, \ \bar{u}^{C} &= \{\bar{u}_{1}^{C},\bar{u}_{1}^{C}\} \text{ with } |\bar{u}_{1}^{B}| = |\bar{u}_{1}^{C}| = k \text{ for } k = 0, \dots, a \\ \bar{v}^{B} &= \{\bar{v}_{1}^{B},\bar{v}_{1}^{B}\}, \ \bar{v}^{C} &= \{\bar{v}_{1}^{C},\bar{v}_{1}^{C}\} \text{ with } |\bar{v}_{1}^{B}| = |\bar{v}_{1}^{C}| = n \text{ for } n = 0, \dots, b. \end{split}$$

 $Z_{a,b}$ so-called highest coefficient

$$Z_{a,b}(\bar{t};\bar{x}|\bar{s};\bar{y})=(-1)^b\sum \mathcal{K}_b(\bar{s}-c|\bar{w}_{\mathrm{I}})\mathcal{K}_a(\bar{w}_{\mathrm{II}}|\bar{t})\mathcal{K}_b(\bar{y}|\bar{w}_{\mathrm{I}})f(\bar{w}_{\mathrm{I}},\bar{w}_{\mathrm{II}}).$$

But $S_{a,b}$ difficult to handle.....

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Here we consider the scalar product of an on-shell Bethe vector

$$t(x) \mathbb{B}^{a,b}(\bar{u}^B; \bar{v}^B) = \tau(x|\bar{u}^B, \bar{v}^B) \mathbb{B}^{a,b}(\bar{u}^B; \bar{v}^B)$$
 and BAEs

with a twisted dual on-shell Bethe vector

$$\mathbb{C}^{a,b}_{\kappa}(\bar{u}^{C};\bar{v}^{C}) t_{\kappa}(x) = \tau_{\kappa}(x|\bar{u}^{C},\bar{v}^{C}) \mathbb{C}^{a,b}_{\kappa}(\bar{u}^{C};\bar{v}^{C})$$
with twisted BAEs

$$t_{\kappa}(x) = tr(M T(x)) \quad \text{with} \quad M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \kappa & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
$$t_{\kappa}(x) = T_{11}(x) + \kappa T_{22}(x) + T_{33}(x)$$

$$\mathcal{S}_{a,b} \equiv \mathcal{S}_{a,b}(\bar{u}^{\mathsf{C}}, \bar{u}^{\mathsf{B}} | \bar{v}^{\mathsf{C}}, \bar{v}^{\mathsf{B}}) = \mathbb{C}^{a,b}_{\kappa}(\bar{u}^{\mathsf{C}}; \bar{v}^{\mathsf{C}}) \mathbb{B}^{a,b}(\bar{u}^{\mathsf{B}}; \bar{v}^{\mathsf{B}})$$

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$$\begin{split} \mathcal{S}_{a,b} &= f(\bar{v}^{\scriptscriptstyle C},\bar{u}^{\scriptscriptstyle C})f(\bar{v}^{\scriptscriptstyle B},\bar{u}^{\scriptscriptstyle B})t(\bar{v}^{\scriptscriptstyle C},\bar{u}^{\scriptscriptstyle B})\Delta_a'(\bar{u}^{\scriptscriptstyle C})\Delta_a(\bar{u}^{\scriptscriptstyle B})\Delta_b'(\bar{v}^{\scriptscriptstyle C})\Delta_b(\bar{v}^{\scriptscriptstyle B})\\ &\times \det_{a+b}\mathcal{M}, \end{split}$$

$$\Delta'_n(\bar{x}) = \prod_{j>k}^n g(x_j, x_k), \qquad \Delta_n(\bar{y}) = \prod_{j$$

 \mathcal{M} is a $(a+b) \times (a+b)$ matrix. For $\bar{y} = \{\bar{u}^{\scriptscriptstyle B}, \bar{v}^{\scriptscriptstyle C}\}$:

$$egin{array}{rcl} \mathcal{M}_{j,k} &=& \displaystylerac{c}{g(y_k,ar{u}^c)g(ar{v}^c,y_k)}rac{\partial au_k^c(y_k|ar{u}^c,ar{v}^c)}{\partial u_j^c}, & j=1,\ldots,a, \ \mathcal{M}_{a+j,k} &=& \displaystylerac{-c}{g(y_k,ar{u}^B)g(ar{v}^B,y_k)}rac{\partial au(y_k|ar{u}^B,ar{v}^B)}{\partial v_j^B}, & j=1,\ldots,b. \end{array}$$

Similar expression for $\mathcal{S}_{a,b}$ when considering a general twist

$$t_{\bar{\kappa}}(x) = \kappa_1 T_{11}(x) + \kappa_2 T_{22}(x) + \kappa_3 T_{33}(x)$$

but up to terms $(\kappa_i - 1)(\kappa_j - 1)$, i, j = 1, 2, 3

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$$\mathcal{F}_{a,b}^{(i,j)}(z) = \mathbb{C}^{a',b'}(\bar{u}^{c};\bar{v}^{c}) T_{ij}(z) \mathbb{B}^{a,b}(\bar{u}^{B};\bar{v}^{B}), a' = a + \delta_{i1} - \delta_{j1}, \qquad b' = b + \delta_{j3} - \delta_{i3}, \quad i, j = 1, 2, 3.$$

Both $\mathbb{C}^{a',b'}(\bar{u}^c;\bar{v}^c)$ and $\mathbb{B}^{a,b}(\bar{u}^B;\bar{v}^B)$ are on-shell Bethe vectors

 $\mathcal{F}^{(1,2)}_{a,b}(z) = \mathcal{H}_{a',b} \operatorname{det}_{a'+b} \mathcal{N},$

$$\begin{aligned} \mathcal{H}_{a',b} &= \quad \frac{\Delta_{a'}'(\bar{u}^{\scriptscriptstyle C})\Delta_b'(\bar{v}^{\scriptscriptstyle B})\Delta_{a+b+1}(\bar{x})}{h(\bar{v}^{\scriptscriptstyle C},\bar{u}^{\scriptscriptstyle B})} , \quad \bar{x} = \{\bar{u}^{\scriptscriptstyle B},\bar{v}^{\scriptscriptstyle C},z\} \\ \mathcal{N}_{j,k} &= \quad \frac{c}{g(x_k,\bar{u}^{\scriptscriptstyle C})g(\bar{v}^{\scriptscriptstyle C},x_k)} \frac{\partial\tau(x_k|\bar{u}^{\scriptscriptstyle C},\bar{v}^{\scriptscriptstyle C})}{\partial u_j^{\scriptscriptstyle C}}, \quad j=1,\ldots,a', \\ \mathcal{N}_{a'+j,k} &= \quad \frac{-c}{g(x_k,\bar{u}^{\scriptscriptstyle B})g(\bar{v}^{\scriptscriptstyle B},x_k)} \frac{\partial\tau(x_k|\bar{u}^{\scriptscriptstyle B},\bar{v}^{\scriptscriptstyle B})}{\partial v_j^{\scriptscriptstyle B}}, \quad j=1,\ldots,b. \end{aligned}$$

Similar expression for all $\mathcal{F}_{a,b}^{(i,j)}(z)$, |i-j| = 1.

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Form factors (diagonal case)

$$\mathcal{F}^{(s,s)}_{a,b}(z) = (-1)^b \, \mathcal{H}_{a',b} \cdot \det_{a+b+1} \mathcal{N}^{(s)}$$

$$\mathcal{N}_{j,k}^{(s)} = \mathcal{N}_{j,k}, \qquad j = 1, \dots, a+b, \qquad k = 1, \dots, a+b+1;$$

The last line of $\mathcal{N}^{(s)}$ depends on *s*, for instance:

$$\begin{split} \mathcal{N}_{a+b+1,k}^{(1)} &= h(x_k, \bar{u}^B) h(\bar{v}^C, x_k) \left\{ \frac{u_k^B}{c} \left(\frac{f(\bar{v}^B, u_k^B)}{f(\bar{v}^C, u_k^B)} - 1 \right) - 1 \right\}, \\ k &= 1, \dots, a; \\ \mathcal{N}_{a+b+1,a+k}^{(1)} &= h(x_{a+k}, \bar{u}^B) h(\bar{v}^C, x_{a+k}) \left\{ \frac{v_k^C + c}{c} \left(\frac{f(v_k^C, \bar{u}^C)}{f(v_k^C, \bar{u}^B)} - 1 \right) - 1 \right\} \\ k &= 1, \dots, b; \\ \mathcal{N}_{a+b+1,a+b+1}^{(1)} &= \frac{r_1(z)f(\bar{u}^B, z)}{g(\bar{v}^C, z)g(z, \bar{u}^B)} \end{split}$$

 $\begin{array}{l} \mathcal{N}^{(3)} \text{ has a similar expression;} \\ \mathcal{N}^{(2)}_{a+b+1,k} = h(x_k, \bar{u}^{\scriptscriptstyle B})h(\bar{v}^{\scriptscriptstyle C}, x_k), \; k=1,...,a+b+1. \end{array}$

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Form factors (remaining)

- $\mathcal{F}_{a,b}^{(s,s)}(z)$ are computed using the trick of "twisted BVs":

$$\mathcal{F}^{(s,s)}_{a,b}(z) = \frac{d}{d\kappa_s} \left[\mathbb{C}^{a,b}_{\bar{\kappa}}(\bar{u}^C;\bar{v}^C)(t_{\bar{\kappa}}(z) - t(z)) \mathbb{B}^{a,b}(\bar{u}^B;\bar{v}^B) \right]_{\bar{\kappa}=1}$$

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Summary

For models with GL(3) invariant *R*-matrix, we got:

- Explicit expressions for (off-shell) Bethe vectors and their duals
- Multiple action of monodromy elements on these BVs

Both results in term of Izergin-Korepin determinants and sums of partitions of sets of Bethe parameters

- Calculation of the scalar product of (twisted) on-shell BVs
- Calculation of the form factors of $T_{ij}(x)$, i, j = 1, 2, 3

Both results in term of a single determinant (and product of scalar functions)

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- Explicit expression of BVs for U_q(gl_N) arXiv:1310.3253 Use of projectors method in current realization of U_q(gl_N), see works of Khoroshkin, Pakuliak and collaborators arXiv:math/0610398, arXiv:math/0610433, arXiv:math/0610517, arXiv:0711.2819, arXiv:0810.3135, arXiv:1012.1455, etc...
- Multiple actions of $T_{ij}(\bar{w})$ for $U_q(gl_3)$ arXiv:1304.7602
- Scalar products in U_q(gl₃): q-deformed Reshethekhin like formula arXiv:1311.3500, arXiv:1401.4355

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Conclusion: still a lot to do...

- Calculation of the scalar product of generic off-shell BVs (as a single determinant)
 See for instance recent work of Wheeler, arXiv:1306.0552
- Complete calculation of correlation functions, asymptotics, etc...
- Generalization to other models
 - Calculation of the form factors of $T_{jk}(x)$, for $U_q(gl_3)$
 - Case of U_q(gl_N) algebras

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Thank you!

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$\mathcal{F}_{a,b}^{(1,3)}(z)$ form factor

$$\begin{aligned} \mathcal{F}_{a,b}^{(1,3)}(z) &= \mathbb{C}^{a+1,b+1}(\bar{u}^{C};\bar{v}^{C})T_{13}(z)\mathbb{B}^{a,b}(\bar{u}^{B};\bar{v}^{B}) \\ &= (-1)^{b+1}\mathcal{H}_{a+1,b} \cdot \det_{a+b+2}\mathcal{N}^{(1,3)}, \\ \mathcal{N}_{j,k}^{(1,3)} &= \mathcal{N}_{j,k}, \quad j,k=1,\ldots,a+b+1; \\ \mathcal{N}_{a+b+2,k}^{(1,3)} &= (-1)^{b+1}r_{3}(x_{k})\frac{h(x_{k},\bar{v}^{B})}{g(x_{k},\bar{u}^{B})} + h(\bar{v}^{B},x_{k})h(x_{k},\bar{u}^{B}). \end{aligned}$$

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Explicit formulas

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{K_{k}(\bar{v}_{1}|\bar{u}_{1})}{\lambda_{2}(\bar{v}_{\Pi})\lambda_{2}(\bar{u})} \frac{f(\bar{v}_{\Pi},\bar{v}_{1})f(\bar{u}_{\Pi},\bar{u}_{1})}{f(\bar{v}_{\Pi},\bar{u})f(\bar{v}_{\Pi},\bar{u}_{1})} T_{12}(\bar{u}_{\Pi})T_{13}(\bar{u}_{\Pi})T_{23}(\bar{v}_{\Pi})|0\rangle$$

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{K_{k}(\bar{v}_{1}|\bar{u}_{1})}{\lambda_{2}(\bar{u}_{\Pi})\lambda_{2}(\bar{v})} \frac{f(\bar{v}_{\Pi},\bar{v}_{\Pi})f(\bar{v}_{\Pi},\bar{u}_{\Pi})}{f(\bar{v}_{\Pi},\bar{u}_{1})f(\bar{v},\bar{u}_{\Pi})} T_{23}(\bar{v}_{\Pi})T_{13}(\bar{v}_{1})T_{12}(\bar{u}_{\Pi})|0\rangle$$

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{K_{k}(\bar{v}_{1}|\bar{u}_{1})}{\lambda_{2}(\bar{v}_{\Pi})\lambda_{2}(\bar{u})} \frac{f(\bar{v}_{\Pi},\bar{v}_{1})f(\bar{u}_{\Pi},\bar{u}_{\Pi})}{f(\bar{v},\bar{u})} T_{13}(\bar{u}_{\Pi})T_{12}(\bar{u}_{\Pi})T_{23}(\bar{v}_{\Pi})|0\rangle$$

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{K_{k}(\bar{v}_{1}|\bar{u}_{1})}{\lambda_{2}(\bar{u}_{\Pi})\lambda_{2}(\bar{v})} \frac{f(\bar{v}_{\Pi},\bar{v}_{1})f(\bar{u}_{\Pi},\bar{u}_{\Pi})}{f(\bar{v},\bar{u})} T_{13}(\bar{v}_{1})T_{23}(\bar{v}_{\Pi})T_{12}(\bar{u}_{\Pi})|0\rangle$$

$$\mathbb{B}^{a,b}(\bar{u};\bar{v}) = \sum \frac{K_{k}(\bar{v}_{1}|\bar{u}_{1})}{\lambda_{2}(\bar{u}_{\Pi})\lambda_{2}(\bar{v})} \frac{f(\bar{v}_{\Pi},\bar{v}_{1})f(\bar{u}_{\Pi},\bar{u}_{\Pi})}{f(\bar{v},\bar{u})} T_{13}(\bar{v}_{1})T_{23}(\bar{v}_{\Pi})T_{12}(\bar{u}_{\Pi})|0\rangle$$

The sums are taken over partitions of the sets $\bar{u} \Rightarrow \{\bar{u}_{I}, \bar{u}_{II}\}$ and $\bar{v} \Rightarrow \{\bar{v}_{I}, \bar{v}_{II}\}$ with $0 \le |\bar{u}_{I}| = |\bar{v}_{I}| = k \le \min(a, b)$.

 $K_k(\bar{v}_I | \bar{u}_I)$ is the Izergin–Korepin determinant

$$\mathsf{K}_k(\bar{x}|\bar{y}) = \prod_{\ell < m}^k g(x_\ell, x_m) g(y_m, y_\ell) \cdot h(\bar{x}, \bar{y}) \, \det_k \left[t(x_i, y_j) \right].$$

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The matrix $\ensuremath{\mathcal{M}}$

Diagonal blocks

$$\begin{aligned} \mathcal{M}^{(u)}(u_j^C, u_k^B) &= h(\bar{v}^C, u_k^B) h(u_k^B, \bar{u}^C) \Big[\kappa t(u_k^B, u_j^C) \\ \mathbf{a} \times \mathbf{a} \text{ block} &+ t(u_j^C, u_k^B) \frac{f(\bar{v}^B, u_k^B)}{f(\bar{v}^C, u_k^B)} \frac{h(\bar{u}^C, u_k^B)h(u_k^B, \bar{u}^B)}{h(u_k^B, \bar{u}^C)h(\bar{u}^B, u_k^B)} \Big] \\ \mathcal{M}^{(v)}(v_j^B, v_k^C) &= h(v_k^C, \bar{u}^B)h(\bar{v}^B, v_k^C) \Big[t(v_j^B, v_k^C) \\ \mathbf{b} \times \mathbf{b} \text{ block} &+ \kappa t(v_k^C, v_j^B) \frac{f(v_k^C, \bar{u}^C)}{f(v_k^C, \bar{u}^B)} \frac{h(\bar{v}^C, v_k^C)h(v_k^C, \bar{v}^B)}{h(v_k^C, \bar{v}^C)h(\bar{v}^B, v_k^C)} \Big] \end{aligned}$$

Off-diagonal blocks

$$\mathcal{M}^{(u)}(u_j^C, v_k^C) = \kappa t(v_k^C, u_j^C) h(v_k^C, \bar{u}^C) h(\bar{v}^C, v_k^C) \qquad a \times b \text{ block}$$
$$\mathcal{M}^{(v)}(v_j^B, u_k^B) = t(v_j^B, u_k^B) h(\bar{v}^B, u_k^B) h(u_k^B, \bar{u}^B) \qquad b \times a \text{ block}$$

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