## Spin chains based on (quantum) gl(3) algebras: Bethe vectors, scalar products and form factors

Spin chains based on (quantum) $\mathrm{gl}(3)$ algebras: Bethe vectors, scalar products and form factors

Eric Ragoucy

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arXiv:1206.4931, arXiv:1207.0956, arXiv:1210.0768, arXiv:1211.3968 arXiv:1304.7602, arXiv:1310.3253, arXiv:1311.3500, arXiv:1312.1488
arXiv:1401.4355, arXiv:1406.5125


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## General background: Integrable spin chains

## Rational or trigonometric $9 \times 9 R$-matrix

$$
R(x, y) \in V \otimes V \text { with } V=\operatorname{End}\left(\mathbb{C}^{3}\right)
$$

$R(x, y)$ obeys Yang-Baxter equation (in $V \otimes V \otimes V$ ) $R^{12}\left(x_{1}, x_{2}\right) R^{13}\left(x_{1}, x_{3}\right) R^{23}\left(x_{2}, x_{3}\right)=R^{23}\left(x_{2}, x_{3}\right) R^{13}\left(x_{1}, x_{3}\right) R^{12}\left(x_{1}, x_{2}\right)$

It is associated to a quantum group $\mathcal{A}$ which is:

- The Yangian $\mathcal{A}=Y(g / 3)$ when $R(x, y)$ is rational (XXX chain)
- The affine quantum group $\mathcal{A}=U_{q}\left(\widehat{g}_{3}\right)$ when $R(x, y)$ is trigonometric (XXZ chain)

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## General background: Integrable spin chains

Rational or trigonometric $9 \times 9 R$-matrix
$R(x, y) \in V \otimes V$ with $V=\operatorname{End}\left(\mathbb{C}^{3}\right)$
$R(x, y)$ obeys Yang-Baxter equation (in $V \otimes V \otimes V$ ) $R^{12}\left(x_{1}, x_{2}\right) R^{13}\left(x_{1}, x_{3}\right) R^{23}\left(x_{2}, x_{3}\right)=R^{23}\left(x_{2}, x_{3}\right) R^{13}\left(x_{1}, x_{3}\right) R^{12}\left(x_{1}, x_{2}\right)$

It is associated to a quantum group $\mathcal{A}$ which is:

- The Yangian $\mathcal{A}=Y(g / 3)$ when $R(x, y)$ is rational (XXX chain)
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For the talk, rational $R$-matrix:

$$
R(x, y)=\mathbf{I}+g(x, y) \mathbf{P} \in \operatorname{End}\left(\mathbb{C}^{3}\right) \otimes \operatorname{End}\left(\mathbb{C}^{3}\right) \quad \text { and } \quad g(x, y)=\frac{c}{x-y}
$$

$\mathbf{I}$ is the identity matrix, $\mathbf{P}$ is the permutation matrix between two spaces $\operatorname{End}\left(\mathbb{C}^{3}\right), c$ is a constant.

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## Monodromy matrix

$$
T(x)=\sum_{i, j=1}^{3} e_{i j} \otimes T_{i j}(x) \in \operatorname{End}\left(\mathbb{C}^{3}\right) \otimes \mathcal{A}
$$

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## Choice of a $Y(g / 3)$ (lowest weight) representation:

$$
T_{j j}(w)|0\rangle=\lambda_{j}(w)|0\rangle, j=1,2,3 \quad T_{i j}(w)|0\rangle=0, \quad 1 \leq j<i \leq 3
$$

Up to normalisation $T(w) \rightarrow \lambda_{2}^{-1}(w) T(w)$, only need the ratios

$$
r_{1}(w)=\frac{\lambda_{1}(w)}{\lambda_{2}(w)}, \quad r_{3}(w)=\frac{\lambda_{3}(w)}{\lambda_{2}(w)}
$$

where $r_{1}$ and $r_{3}$ are free functional parameters.

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## Aim

Compute the correlation functions $<\mathcal{O}_{1} \cdots \mathcal{O}_{n}>=\operatorname{tr}\left(\mathcal{O}_{1} \cdots \mathcal{O}_{n}\right)$ for some local operators $\mathcal{O}_{1}, \cdots, \mathcal{O}_{n}$

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If one has a basis of the space of states $\mathcal{H},\{\mid \psi>\}$, then it is enough to compute $\left\langle\psi^{\prime}\right| \mathcal{O}_{1} \cdots \mathcal{O}_{n}|\psi\rangle$
Since we have a basis $\mathcal{O}|\psi\rangle=\sum\left\langle\psi^{\prime}\right| \mathcal{O}|\psi\rangle\left|\psi^{\prime}\right\rangle$, and we need "only" < $\psi \mid \psi^{\prime}>$

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## Aim

- Compute Bethe vectors (BVs), eigenvectors of $t(x)$ :

$$
t(x) \mathbb{B}^{a, b}(\bar{u}, \bar{v})=\tau(x \mid \bar{u}, \bar{v}) \mathbb{B}^{a, b}(\bar{u}, \bar{v}) \Rightarrow \text { Bethe ansatz eqs (BAE) }
$$

- Action of $T_{i j}(\bar{x})$ on $\mathbb{B}^{a, b}(\bar{u}, \bar{v})$
- Scalar product of off-shell BVs (without BAE)
- Form factors $\mathbb{C}^{a, b}(\bar{t}, \bar{s}) T_{i j}(\bar{x}) \mathbb{B}^{a, b}(\bar{u}, \bar{v})$

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## Plan of the talk

- Bethe vectors (BVs)
- Multiple actions of Yangian generators on BVs
- Scalar products of BVs
- Form factors and correlation functions
- Conclusion


## Calculations are rather technical $\Rightarrow$ results only!

Presentation for $Y\left(g l_{3}\right)$ but most of the results are valid for $U_{q}\left(g l_{3}\right)$ (see at the end)

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Apart from the functions $g(x, y)=\frac{c}{x-y}, r_{1}(x)$ and $r_{3}(x)$ we introduce

$$
f(x, y)=\frac{x-y+c}{x-y}, \quad h(x, y)=\frac{f(x, y)}{g(x, y)}, \quad t(x, y)=\frac{g(x, y)}{h(x, y)}
$$

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$$

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- |. $\mid$ is the dimension of a set: $\bar{w}=\left\{w_{1}, w_{2}\right\} \Rightarrow|\bar{w}|=2$, etc...
- Individual elements of the sets have latin subscripts: $w_{j}, u_{k}$, etc..
- Subsets of variables are denoted by roman indices: $\bar{u}_{\mathrm{I}}, \bar{v}_{\mathrm{iv}}, \bar{w}_{\mathrm{II}}$, etc.
- Special case: $\bar{u}_{j}=\bar{u} \backslash\left\{u_{j}\right\}, \bar{w}_{k}=\bar{w} \backslash\left\{w_{k}\right\}$, etc...

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$$
f(x, y)=\frac{x-y+c}{x-y}, \quad h(x, y)=\frac{f(x, y)}{g(x, y)}, \quad t(x, y)=\frac{g(x, y)}{h(x, y)} .
$$

- "bar" always denote sets of variables: $\bar{w}, \bar{u}, \bar{v}$ etc..
- |. $\mid$ is the dimension of a set: $\bar{w}=\left\{w_{1}, w_{2}\right\} \Rightarrow|\bar{w}|=2$, etc...
- Individual elements of the sets have latin subscripts: $w_{j}, u_{k}$, etc..
- Subsets of variables are denoted by roman indices: $\bar{u}_{\mathrm{I}}, \bar{v}_{\mathrm{iv}}, \bar{w}_{I I}$, etc.
- Special case: $\bar{u}_{j}=\bar{u} \backslash\left\{u_{j}\right\}, \bar{w}_{k}=\bar{w} \backslash\left\{w_{k}\right\}$, etc...


## Shorthand notations for products of scalar functions:

$$
\begin{aligned}
& f\left(\bar{u}_{\text {II }}, \bar{u}_{\text {I }}\right)=\prod_{u_{j} \in \bar{u}_{\mathrm{I}}} \prod_{u_{k} \in \bar{u}_{\mathrm{I}}} f\left(u_{j}, u_{k}\right), \\
& r_{1}\left(\bar{u}_{\text {II }}\right)=\prod_{u_{j} \in \bar{u}_{\mathrm{II}}} r_{1}\left(u_{j}\right) ; \quad g\left(v_{k}, \bar{w}\right)=\prod_{w_{j} \in \bar{w}} g\left(v_{k}, w_{j}\right), \quad \text { etc.. }
\end{aligned}
$$

## Bethe vectors

Framework: Algebraic-Nested Bethe ansatz (Leningrad school 80's) [Faddeev, Kulish, Reshetikhin, Sklyanin, Takhtajan]

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## On-shell Bethe vectors

$$
t(x) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\tau(x \mid \bar{u} ; \bar{v}) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})
$$

$\bar{u}=\left\{u_{1}, \ldots, u_{a}\right\}$ and $\bar{v}=\left\{v_{1}, \ldots, v_{b}\right\}$ are the Bethe parameters. $t(x)$-eigenvectors provided $\bar{u}$ and $\bar{v}$ obey the Bethe equations (BAEs):

$$
\begin{aligned}
r_{1}\left(\bar{u}_{\mathrm{I}}\right) & =\frac{f\left(\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{II}}\right)}{f\left(\bar{u}_{\mathrm{II}}, \bar{u}_{\mathrm{I}}\right)} f\left(\bar{v}, \bar{u}_{\mathrm{I}}\right), \\
r_{3}\left(\bar{v}_{\mathrm{I}}\right) & =\frac{f\left(\bar{v}_{\mathrm{II}}, \bar{v}_{\mathrm{I}}\right)}{f\left(\bar{v}_{\mathrm{I}}, \bar{v}_{\text {II }}\right)} f\left(\bar{v}_{\mathrm{I}}, \bar{u}\right) .
\end{aligned}
$$

that hold for arbitrary partitions of the sets $\bar{u}$ and $\bar{v}$ into subsets $\left\{\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{II}}\right\}$ and $\left\{\bar{v}_{\mathrm{I}}, \bar{v}_{\text {II }}\right\}$.

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## Known formulas: Trace formula ['07 Tarasov \& Varchenko]

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$$
\mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\operatorname{tr}\left(\mathbb{T}(\bar{u} ; \bar{v}) \mathbb{R}(\bar{u} ; \bar{v}) e_{21}^{\otimes a} \otimes e_{32}^{\otimes b}\right) \in Y(g / 3)
$$

where $\mathbb{T}$ is some product of $T(x)$ 's and $\mathbb{R}$ of $R$-matrices.

## Recursion formulas

$$
\begin{aligned}
& \lambda_{2}\left(u_{k}\right) f\left(\bar{v}, u_{k}\right) \mathbb{B}^{a+1, b}(\bar{u} ; \bar{v})=T_{12}\left(u_{k}\right) \mathbb{B}^{a, b}\left(\bar{u}_{k} ; \bar{v}\right)+ \\
& +\sum_{i=1}^{b} g\left(v_{i}, u_{k}\right) f\left(\bar{v}_{i}, v_{i}\right) T_{13}\left(u_{k}\right) \mathbb{B}^{a, b-1}\left(\bar{u}_{k} ; \bar{v}_{i}\right) \\
& \begin{aligned}
& \lambda_{2}\left(v_{k}\right) f\left(v_{k}, \bar{u}\right) \mathbb{B}^{a, b+1}(\bar{u} ; \bar{v})=T_{23}\left(v_{k}\right) \mathbb{B}^{a, b}\left(\bar{u} ; \bar{v}_{k}\right)+ \\
&+\sum_{j=1}^{a} g\left(v_{k}, u_{j}\right) f\left(u_{j}, \bar{u}_{j}\right) T_{13}\left(v_{k}\right) \mathbb{B}^{a-1, b}\left(\bar{u}_{j} ; \bar{v}_{k}\right)
\end{aligned}
\end{aligned}
$$

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## Explicit formulas

$\mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\sum \frac{\mathrm{K}_{k}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)}{\lambda_{2}\left(\bar{v}_{\text {II }}\right) \lambda_{2}(\bar{u})} \frac{f\left(\bar{v}_{\text {II }}, \bar{v}_{\mathrm{I}}\right) f\left(\bar{u}_{\text {II }}, \bar{u}_{\mathrm{I}}\right)}{f\left(\bar{v}_{\text {II }}, \bar{u}\right) f\left(\bar{v}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right)} T_{12}\left(\bar{u}_{\text {II }}\right) T_{13}\left(\bar{u}_{\mathrm{I}}\right) T_{23}\left(\bar{v}_{\text {II }}\right)|0\rangle$

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## All these formulas are related

- Explicit expressions obey the recursion formulas
- Trace formula obeys the recursion formulas

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- Recursion formulas uniquely fix the BVs, once $\mathbb{B}^{a, 0}(\bar{u},$.$) or \mathbb{B}^{0, b}(., \bar{v})$ are known.

Bethe vectors $\mathbb{B}^{a, b}(\bar{u} ; \bar{v}),|\bar{u}|=a,|\bar{v}|=b$

- On-shell BVs: $\bar{u}, \bar{v}$ obey BAEs so that

$$
t(x) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\tau(x \mid \bar{u} ; \bar{v}) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})
$$

- Off-shell BVs: $\bar{u}, \bar{v}$ are left free

Dual Bethe vectors $\mathbb{C}^{a, b}(\bar{u} ; \bar{v}),|\bar{u}|=a,|\bar{v}|=b$

- On-shell dual BVs: $\bar{u}, \bar{v}$ obey BAEs so that

$$
\mathbb{C}^{a, b}(\bar{u} ; \bar{v}) t(x)=\tau(x \mid \bar{u} ; \bar{v}) \mathbb{C}^{a, b}(\bar{u} ; \bar{v})
$$

- Off-shell dual BVs: $\bar{u}, \bar{v}$ are left free


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## Correlation functions

## How to compute $\mathcal{O}_{\mathbb{C}, \mathbb{B}}=\langle\mathbb{C}| \mathcal{O}|\mathbb{B}\rangle$ ?

If $|\mathbb{B}\rangle$ is a complete basis (of transfer matrix eigenvectors), then

$$
\begin{equation*}
\mathcal{O}|\mathbb{B}\rangle=\sum_{\mathbb{B}^{\prime}} \mathbb{O}_{\mathbb{B} \mathbb{B}^{\prime}}\left|\mathbb{B}^{\prime}\right\rangle \tag{1}
\end{equation*}
$$

$\rightarrow$ what is needed is $\left\langle\mathbb{C} \mid \mathbb{B}^{\prime}\right\rangle$ and (1)

$$
\text { Local operators: } \mathcal{O}=\sum_{\ell=1}^{L} \sum_{i, j=1}^{3} \mathcal{O}_{i j}^{(\ell)} e_{i j}^{\ell} \Rightarrow\langle\mathbb{C}| e_{i j}^{\ell}|\mathbb{B}\rangle
$$

## Further simplification: QISM

Expression of $e_{i j}^{\ell}, i, j=1,2,3$ and $\ell=1, \ldots L$, in terms of monodromy entries $T_{k l}(x)$ ['00 Maillet \& Terras]:

$$
e_{i j}^{\ell}=(t(0))^{\ell-1} T_{i j}(0)(t(0))^{-\ell}
$$

$\Rightarrow$ we need "only" $T_{k l}(x) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})$ and $\quad \mathbb{C}^{a, b}(\bar{w} ; \bar{z}) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})$

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$$
T_{12}(\bar{x}) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=(-1)^{n} \lambda_{2}(\bar{x}) \sum f\left(\bar{\xi}_{\Pi}, \bar{\xi}_{\mathrm{I}}\right) \mathrm{K}_{n}\left(\bar{\xi}_{\mathrm{I}} \mid \bar{x}+c\right) \mathbb{B}^{a+n, b}\left(\bar{\eta} ; \bar{\xi}_{\Pi}\right)
$$

Sum on partitions $\bar{\xi}=\left\{\bar{\xi}_{\mathrm{I}} ; \bar{\xi}_{\mathrm{II}}\right\}$ with $\left|\bar{\xi}_{\mathrm{I}}\right|=n$

$$
T_{23}(\bar{x}) \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=(-1)^{n} \lambda_{2}(\bar{x}) \sum f\left(\bar{\eta}_{\mathrm{I}}, \bar{\eta}_{\mathrm{II}}\right) \mathrm{K}_{n}\left(\bar{x} \mid \bar{\eta}_{\mathrm{I}}+c\right) \mathbb{B}^{a, b+n}\left(\bar{\eta}_{\mathrm{I}} ; \bar{\xi}\right) .
$$

Sum on partitions $\bar{\eta}=\left\{\bar{\eta}_{\mathrm{I}} ; \bar{\eta}_{\mathrm{I}}\right\}$ with $\left|\bar{\eta}_{\mathrm{I}}\right|=n$

Imply recursion relations as a subcase ( $\mathrm{n}=1$ )
Similar expressions for any $T_{i j}(\bar{x})$ and for dual BVs

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## Scalar products of BV s

$$
\mathcal{S}_{a, b} \equiv \mathcal{S}_{a, b}\left(\bar{u}^{C}, \bar{u}^{B} \mid \bar{v}^{C}, \bar{v}^{B}\right)=\mathbb{C}^{a, b}\left(\bar{u}^{C} ; \bar{v}^{C}\right) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right)
$$

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Superscripts ${ }^{B}$ and ${ }^{C}$ to denote different sets of parameters!

## General formula given by Reshetikhin

$$
\begin{aligned}
& \mathcal{S}_{a, b}=\sum r_{1}\left(\bar{u}_{\mathrm{I}}^{B}\right) r_{1}\left(\bar{u}_{\mathrm{II}}^{C}\right) r_{3}\left(\bar{v}_{\mathrm{I}}^{B}\right) r_{3}\left(\bar{v}_{\text {II }}^{C}\right) \\
& \times f\left(\bar{u}_{\text {I }}^{C}, \bar{u}_{\text {II }}^{C}\right) f\left(\bar{u}_{\text {II }}^{B}, \bar{u}_{\text {I }}^{B}\right) f\left(\bar{v}_{\text {II }}^{C}, \bar{v}_{\text {I }}^{C}\right) f\left(\bar{v}_{\text {I }}^{B}, \bar{v}_{\text {II }}^{B}\right) f\left(\bar{v}_{\text {I }}^{C}, \bar{u}_{\text {I }}^{C}\right) f\left(\bar{v}_{\text {II }}^{B}, \bar{u}_{\text {II }}^{B}\right) \\
& \times Z_{a-k, n}\left(\bar{u}_{I I}^{C} ; \bar{u}_{\mathrm{II}}^{B} \mid \bar{v}_{\mathrm{I}}^{C} ; \bar{v}_{\mathrm{I}}^{B}\right) Z_{k, b-n}\left(\bar{u}_{\mathrm{I}}^{B} ; \bar{u}_{\mathrm{I}}^{C} \mid \bar{v}_{\mathrm{II}}^{B} ; \bar{v}_{\mathrm{II}}^{C}\right) \\
& \bar{u}^{B}=\left\{\bar{u}_{\mathrm{I}}^{B}, \bar{u}_{\mathrm{I}}^{B}\right\}, \bar{u}^{C}=\left\{\bar{u}_{\mathrm{I}}^{C}, \bar{u}_{\mathrm{I}}^{C}\right\} \text { with }\left|\bar{u}_{\mathrm{I}}^{B}\right|=\left|\bar{u}_{\mathrm{I}}^{C}\right|=k \text { for } k=0, \ldots, a \\
& \bar{v}^{B}=\left\{\bar{v}_{\mathrm{I}}^{B}, \bar{v}_{\mathrm{II}}^{B}\right\}, \bar{v}^{C}=\left\{\bar{v}_{\mathrm{I}}^{C}, \bar{v}_{\mathrm{II}}^{C}\right\} \text { with }\left|\bar{v}_{\mathrm{I}}^{B}\right|=\left|\bar{v}_{\mathrm{I}}^{C}\right|=n \text { for } n=0, \ldots, b \text {. }
\end{aligned}
$$

$Z_{a, b}$ so-called highest coefficient

$$
Z_{a, b}(\bar{t} ; \bar{x} \mid \bar{s} ; \bar{y})=(-1)^{b} \sum K_{b}\left(\bar{s}-c \mid \bar{w}_{\mathrm{I}}\right) K_{a}\left(\bar{w}_{\text {II }} \mid \bar{t}\right) K_{b}\left(\bar{y} \mid \bar{w}_{\mathrm{I}}\right) f\left(\bar{w}_{\mathrm{I}}, \bar{w}_{\text {II }}\right)
$$

But $\mathcal{S}_{a, b}$ difficult to handle.....

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Here we consider the scalar product of an on-shell Bethe vector

$$
t(x) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right)=\tau\left(x \mid \bar{u}^{B}, \bar{v}^{B}\right) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right) \quad \text { and BAEs }
$$

with a twisted dual on-shell Bethe vector

$$
\mathbb{C}_{\kappa}^{a, b}\left(\bar{u}^{C} ; \bar{v}^{C}\right) t_{\kappa}(x)=\tau_{\kappa}\left(x \mid \bar{u}^{C}, \bar{v}^{C}\right) \mathbb{C}_{\kappa}^{a, b}\left(\bar{u}^{C} ; \bar{v}^{C}\right)
$$

with twisted BAEs

$$
\begin{aligned}
& t_{\kappa}(x)=\operatorname{tr}(M T(x)) \quad \text { with } \quad M=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & \kappa & 0 \\
0 & 0 & 1
\end{array}\right) \\
& t_{\kappa}(x)=T_{11}(x)+\kappa T_{22}(x)+T_{33}(x)
\end{aligned}
$$

$$
\mathcal{S}_{a, b} \equiv \mathcal{S}_{a, b}\left(\bar{u}^{C}, \bar{u}^{B} \mid \bar{v}^{C}, \bar{v}^{B}\right)=\mathbb{C}_{\kappa}^{a, b}\left(\bar{u}^{C} ; \bar{v}^{C}\right) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right)
$$

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$$
\begin{aligned}
\mathcal{S}_{a, b}= & f\left(\bar{v}^{C}, \bar{u}^{C}\right) f\left(\bar{v}^{B}, \bar{u}^{B}\right) t\left(\bar{v}^{C}, \bar{u}^{B}\right) \Delta_{a}^{\prime}\left(\bar{u}^{C}\right) \Delta_{a}\left(\bar{u}^{B}\right) \Delta_{b}^{\prime}\left(\bar{v}^{C}\right) \Delta_{b}\left(\bar{v}^{B}\right) \\
& \times \operatorname{det}_{a+b}^{\mathcal{M}}
\end{aligned}
$$

$$
\Delta_{n}^{\prime}(\bar{x})=\prod_{j>k}^{n} g\left(x_{j}, x_{k}\right), \quad \Delta_{n}(\bar{y})=\prod_{j<k}^{n} g\left(y_{j}, y_{k}\right)
$$

$\mathcal{M}$ is a $(a+b) \times(a+b)$ matrix. For $\bar{y}=\left\{\bar{u}^{B}, \bar{v}^{C}\right\}:$

$$
\begin{aligned}
\mathcal{M}_{j, k} & =\frac{c}{g\left(y_{k}, \bar{u}^{C}\right) g\left(\bar{v}^{C}, y_{k}\right)} \frac{\partial \tau_{\kappa}\left(y_{k} \mid \bar{u}^{C}, \bar{v}^{C}\right)}{\partial u_{j}^{C}}, \quad j=1, \ldots, a, \\
\mathcal{M}_{a+j, k} & =\frac{-c}{g\left(y_{k}, \bar{u}^{B}\right) g\left(\bar{v}^{B}, y_{k}\right)} \frac{\partial \tau\left(y_{k} \mid \bar{u}^{B}, \bar{v}^{B}\right)}{\partial v_{j}^{B}}, \quad j=1, \ldots, b .
\end{aligned}
$$

Similar expression for $\mathcal{S}_{a, b}$ when considering a general twist

$$
t_{\bar{\kappa}}(x)=\kappa_{1} T_{11}(x)+\kappa_{2} T_{22}(x)+\kappa_{3} T_{33}(x)
$$

but up to terms $\left(\kappa_{i}-1\right)\left(\kappa_{j}-1\right), i, j=1,2,3$

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## Form factors (off-diagonal case)

$$
\begin{aligned}
& \mathcal{F}_{a, b}^{(i, j)}(z)=\mathbb{C}^{a^{\prime}, b^{\prime}}\left(\bar{u}^{C} ; \bar{v}^{C}\right) T_{i j}(z) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right), \\
& a^{\prime}=a+\delta_{i 1}-\delta_{j 1}, \quad b^{\prime}=b+\delta_{j 3}-\delta_{i 3}, \quad i, j=1,2,3 .
\end{aligned}
$$

Both $\mathbb{C}^{a^{\prime}, b^{\prime}}\left(\bar{u}^{C} ; \bar{v}^{C}\right)$ and $\mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right)$ are on-shell Bethe vectors

$$
\begin{gathered}
\mathcal{F}_{a, b}^{(1,2)}(z)=\mathcal{H}_{a^{\prime}, b} \operatorname{det}_{a^{\prime}+b} \mathcal{N}, \\
\mathcal{H}_{a^{\prime}, b}=\frac{\Delta_{a^{\prime}}^{\prime}\left(\bar{u}^{C}\right) \Delta_{b}^{\prime}\left(\bar{v}^{B}\right) \Delta_{a+b+1}(\bar{x})}{h\left(\bar{v}^{C}, \bar{u}^{B}\right)}, \quad \bar{x}=\left\{\bar{u}^{B}, \bar{v}^{C}, z\right\} \\
\mathcal{N}_{j, k}= \\
\frac{c}{g\left(x_{k}, \bar{u}^{C}\right) g\left(\bar{v}^{C}, x_{k}\right)} \frac{\partial \tau\left(x_{k} \mid \bar{u}^{C}, \bar{v}^{C}\right)}{\partial u_{j}^{C}}, \quad j=1, \ldots, a^{\prime}, \\
\mathcal{N}_{a^{\prime}+j, k}= \\
\frac{-c}{g\left(x_{k}, \bar{u}^{B}\right) g\left(\bar{v}^{B}, x_{k}\right)} \frac{\partial \tau\left(x_{k} \mid \bar{u}^{B}, \bar{v}^{B}\right)}{\partial v_{j}^{B}}, \quad j=1, \ldots, b .
\end{gathered}
$$

Similar expression for all $\mathcal{F}_{a, b}^{(i, j)}(z),|i-j|=1$.

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## Form factors (diagonal case)

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## General

$$
\mathcal{N}_{j, k}^{(s)}=\mathcal{N}_{j, k}, \quad j=1, \ldots, a+b, \quad k=1, \ldots, a+b+1
$$

The last line of $\mathcal{N}^{(s)}$ depends on $s$, for instance:

$$
\begin{aligned}
& \mathcal{N}_{a+b+1, k}^{(1)}=h\left(x_{k}, \bar{u}^{B}\right) h\left(\bar{v}^{C}, x_{k}\right)\left\{\frac{u_{k}^{B}}{c}\left(\frac{f\left(\bar{v}^{B}, u_{k}^{B}\right)}{f\left(\bar{v}^{C}, u_{k}^{B}\right)}-1\right)-1\right\} \\
& \quad k=1, \ldots, a ; \\
& \mathcal{N}_{a+b+1, a+k}^{(1)}=h\left(x_{a+k}, \bar{u}^{B}\right) h\left(\bar{v}^{C}, x_{a+k}\right)\left\{\frac{v_{k}^{C}+c}{c}\left(\frac{f\left(v_{k}^{C}, \bar{u}^{C}\right)}{f\left(v_{k}^{C}, \bar{u}^{B}\right)}-1\right)-1\right\}
\end{aligned}
$$

$$
k=1, \ldots, b
$$

$$
\mathcal{N}_{a+b+1, a+b+1}^{(1)}=\frac{r_{1}(z) f\left(\bar{u}^{B}, z\right)}{g\left(\bar{v}^{C}, z\right) g\left(z, \bar{u}^{B}\right)}
$$

$$
\begin{aligned}
& \mathcal{N}^{(3)} \text { has a similar expression; } \\
& \mathcal{N}_{a+b+1, k}^{(2)}=h\left(x_{k}, \bar{u}^{B}\right) h\left(\bar{v}^{C}, x_{k}\right), k=1, \ldots, a+b+1 .
\end{aligned}
$$

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## Form factors (remaining)

Spin chains based

- $\mathcal{F}_{a, b}^{(i, j)}(z),|i-j|=1$, are computed by brute force, using multiple action of $T_{i j}$ 's
- $\mathcal{F}_{a, b}^{(s, s)}(z)$ are computed using the trick of "twisted BVs":

$$
\mathcal{F}_{a, b}^{(s, s)}(z)=\frac{d}{d \kappa_{s}}\left[\mathbb{C}_{\bar{\kappa}}^{a, b}\left(\bar{u}^{C} ; \bar{v}^{C}\right)\left(t_{\bar{\kappa}}(z)-t(z)\right) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right)\right]_{\bar{\kappa}=1}
$$

- $\mathcal{F}_{a, b}^{(1,3)}(z)$ and $\mathcal{F}_{a, b}^{(3,1)}(z)$ are not computable by these two methods: one needs a new one. We may have found a general one that could help to compute all the form factors in an easy way.
More information soon...


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## Summary

For models with $G L(3)$ invariant $R$-matrix, we got:
Spin chains based on (quantum) $\mathbf{g}(\mathbf{3})$ algebras: Bethe vectors, scalar products and form factors

Eric Ragoucy

- Explicit expressions for (off-shell) Bethe vectors and their duals
- Multiple action of monodromy elements on these BVs

Both results in term of Izergin-Korepin determinants and sums of partitions of sets of Bethe parameters

- Calculation of the scalar product of (twisted) on-shell BVs
- Calculation of the form factors of $T_{i j}(x), i, j=1,2,3$

Both results in term of a single determinant (and product of scalar functions)

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## Case of trigonometric $R$-matrices

> Spin chains based on (quantum) gl(3) algebras: Bethe vectors, scalar products and form factors

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- Explicit expression of BV for $U_{q}\left(g /_{N}\right)$ arXiv:1310.3253 Use of projectors method in current realization of $U_{q}\left(g I_{N}\right)$, see works of Khoroshkin, Pakuliak and collaborators arXiv:math/0610398, arXiv:math/0610433, arXiv:math/0610517, arXiv:0711.2819, arXiv:0810.3135, arXiv:1012.1455, etc...
- Multiple actions of $T_{i j}(\bar{w})$ for $U_{q}(g / 3)$ arXiv:1304.7602
- Scalar products in $U_{q}(g / 3)$ : $q$-deformed Reshethekhin like formula arXiv:1311.3500, arXiv:1401.4355

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## Conclusion: still a lot to do...

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## General

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- Calculation of the scalar product of generic off-shell BVs (as a single determinant)
See for instance recent work of Wheeler, arXiv:1306.0552
- Complete calculation of correlation functions, asymptotics, etc...
- Generalization to other models
- Calculation of the form factors of $T_{j k}(x)$, for $U_{q}\left(g g_{3}\right)$
- Case of $U_{q}\left(g I_{N}\right)$ algebras

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## Thank you!

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## $\mathcal{F}_{a, b}^{(1,3)}(z)$ form factor

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$$
\begin{aligned}
\mathcal{F}_{a, b}^{(1,3)}(z) & =\mathbb{C}^{a+1, b+1}\left(\bar{u}^{C} ; \bar{v}^{C}\right) T_{13}(z) \mathbb{B}^{a, b}\left(\bar{u}^{B} ; \bar{v}^{B}\right) \\
& =(-1)^{b+1} \mathcal{H}_{a+1, b} \cdot \operatorname{det}_{a+b+2} \mathcal{N}^{(1,3)} \\
\mathcal{N}_{j, k}^{(1,3)} & =\mathcal{N}_{j, k}, \quad j, k=1, \ldots, a+b+1 \\
\mathcal{N}_{a+b+2, k}^{(1,3)} & =(-1)^{b+1} r_{3}\left(x_{k}\right) \frac{h\left(x_{k}, \bar{v}^{B}\right)}{g\left(x_{k}, \bar{u}^{B}\right)}+h\left(\bar{v}^{B}, x_{k}\right) h\left(x_{k}, \bar{u}^{B}\right)
\end{aligned}
$$

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## Explicit formulas

$$
\begin{aligned}
& \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\sum \frac{\mathrm{K}_{k}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)}{\lambda_{2}\left(\bar{v}_{\mathrm{I}}\right) \lambda_{2}(\bar{u})} \frac{f\left(\overline{\mathrm{v}}_{\mathrm{I}}, \bar{v}_{\mathrm{I}}\right) f\left(\bar{u}_{\Pi}, \bar{u}_{\mathrm{I}}\right)}{f\left(\bar{v}_{\mathrm{I}}, \bar{u}\right) f\left(\bar{v}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right)} T_{12}\left(\bar{u}_{\mathrm{I}}\right) T_{13}\left(\bar{u}_{\mathrm{I}}\right) T_{23}\left(\bar{v}_{\mathrm{I}}\right)|0\rangle \\
& \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\sum \frac{\mathrm{K}_{k}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)}{\lambda_{2}\left(\bar{u}_{\mathrm{I}}\right) \lambda_{2}(\bar{v})} \frac{f\left(\bar{v}_{\mathrm{I}}, \bar{v}_{\mathrm{I}}\right) f\left(\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right)}{f\left(\bar{v}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right) f\left(\bar{v}, \bar{u}_{\mathrm{I}}\right)} T_{23}\left(\bar{v}_{\text {II }}\right) T_{13}\left(\bar{v}_{\mathrm{I}}\right) T_{12}\left(\bar{u}_{\mathrm{I}}\right)|0\rangle \\
& \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\sum \frac{\mathrm{K}_{\mathrm{k}}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)}{\lambda_{2}\left(\bar{v}_{\mathrm{I}}\right) \lambda_{2}(\bar{u})} \frac{f\left(\bar{v}_{\mathrm{I}}, \bar{v}_{\mathrm{I}}\right) f\left(\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right)}{f(\bar{v}, \bar{u})} T_{13}\left(\bar{u}_{\mathrm{I}}\right) T_{12}\left(\bar{u}_{\mathrm{I}}\right) T_{23}\left(\bar{v}_{\mathrm{I}}\right)|0\rangle \\
& \mathbb{B}^{a, b}(\bar{u} ; \bar{v})=\sum \frac{\mathrm{K}_{k}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)}{\lambda_{2}\left(\bar{u}_{\mathrm{I}}\right) \lambda_{2}(\bar{v})} \frac{f\left(\overline{\mathrm{v}}_{\mathrm{I}}, \bar{v}_{\mathrm{I}}\right) f\left(\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right)}{f(\bar{v}, \bar{u})} T_{13}\left(\bar{v}_{\mathrm{I}}\right) T_{23}\left(\overline{\mathrm{v}}_{\mathrm{II}}\right) T_{12}\left(\bar{u}_{\mathrm{I}}\right)|0\rangle
\end{aligned}
$$

The sums are taken over partitions of the sets
$\bar{u} \Rightarrow\left\{\bar{u}_{\mathrm{I}}, \bar{u}_{\mathrm{I}}\right\}$ and $\bar{v} \Rightarrow\left\{\bar{v}_{\mathrm{I}}, \bar{v}_{I}\right\}$ with $0 \leq\left|\bar{u}_{\mathrm{I}}\right|=\left|\bar{v}_{\mathrm{I}}\right|=k \leq \min (a, b)$.
$\mathrm{K}_{k}\left(\bar{v}_{\mathrm{I}} \mid \bar{u}_{\mathrm{I}}\right)$ is the Izergin-Korepin determinant

$$
\mathrm{K}_{k}(\bar{x} \mid \bar{y})=\prod_{\ell<m}^{k} g\left(x_{\ell}, x_{m}\right) g\left(y_{m}, y_{\ell}\right) \cdot h(\bar{x}, \bar{y}) \operatorname{det}_{k}\left[t\left(x_{i}, y_{j}\right)\right] .
$$

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## Diagonal blocks

$$
\begin{array}{rrr}
\mathcal{M}^{(u)}\left(u_{j}^{C}, u_{k}^{B}\right)= & h\left(\bar{v}^{C}, u_{k}^{B}\right) h\left(u_{k}^{B}, \bar{u}^{C}\right)\left[\kappa t\left(u_{k}^{B}, u_{j}^{C}\right)\right. \\
a \times a \text { block } & \left.+t\left(u_{j}^{C}, u_{k}^{B}\right) \frac{f\left(\bar{v}^{B}, u_{k}^{B}\right)}{f\left(\bar{v}^{C}, u_{k}^{B}\right)} \frac{h\left(\bar{u}^{C}, u_{k}^{B}\right) h\left(u_{k}^{B}, \bar{u}^{B}\right)}{h\left(u_{k}^{B}, \bar{u}^{C}\right) h\left(\bar{u}^{B}, u_{k}^{B}\right)}\right] \\
\mathcal{M}^{(v)}\left(v_{j}^{B}, v_{k}^{C}\right)= & h\left(v_{k}^{C}, \bar{u}^{B}\right) h\left(\bar{v}^{B}, v_{k}^{C}\right)\left[t\left(v_{j}^{B}, v_{k}^{C}\right)\right. \\
b \times b \text { block } & \left.+\kappa t\left(v_{k}^{C}, v_{j}^{B}\right) \frac{f\left(v_{k}^{C}, \bar{u}^{C}\right)}{f\left(v_{k}^{C},,^{B}\right)} \frac{h\left(\bar{v}^{C}, v_{k}^{C}\right) h\left(v_{k}^{C}, \bar{v}^{B}\right)}{h\left(v_{k}^{c}, \bar{v}^{C}\right) h\left(\bar{v}^{B}, v_{k}^{C}\right)}\right]
\end{array}
$$

## Off-diagonal blocks

$$
\begin{array}{ll}
\mathcal{M}^{(u)}\left(u_{j}^{C}, v_{k}^{C}\right)=\kappa t\left(v_{k}^{C}, u_{j}^{C}\right) h\left(v_{k}^{C}, \bar{u}^{C}\right) h\left(\bar{v}^{C}, v_{k}^{C}\right) & a \times b \text { block } \\
\mathcal{M}^{(v)}\left(v_{j}^{B}, u_{k}^{B}\right)=t\left(v_{j}^{B}, u_{k}^{B}\right) h\left(\bar{v}^{B}, u_{k}^{B}\right) h\left(u_{k}^{B}, \bar{u}^{B}\right) & b \times a \text { block }
\end{array}
$$

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